

## Rotating Slipping Torque Sensor DR-2 with Nominal Torque from 1 ... 500 N·m



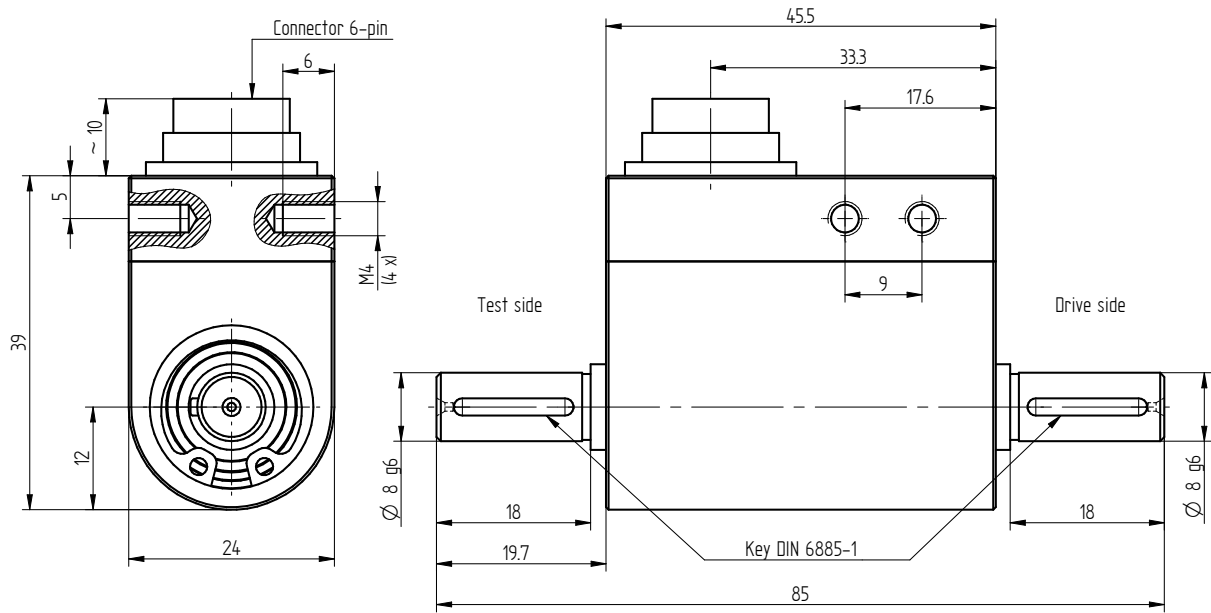
### Performance Features

- Slipping torque sensor for e.g. test bench applications
- High accuracy
- Both shaft ends with feather keys
- Very short axial length
- High torsional stiffness
- Simple handling and assembly
- Special versions on request

### Application

- Process measuring and control technology
- Fully automated machining centres
- Measuring and control devices
- Tool engineering
- Special mechanical engineering

## Dimensions of DR-2 in mm

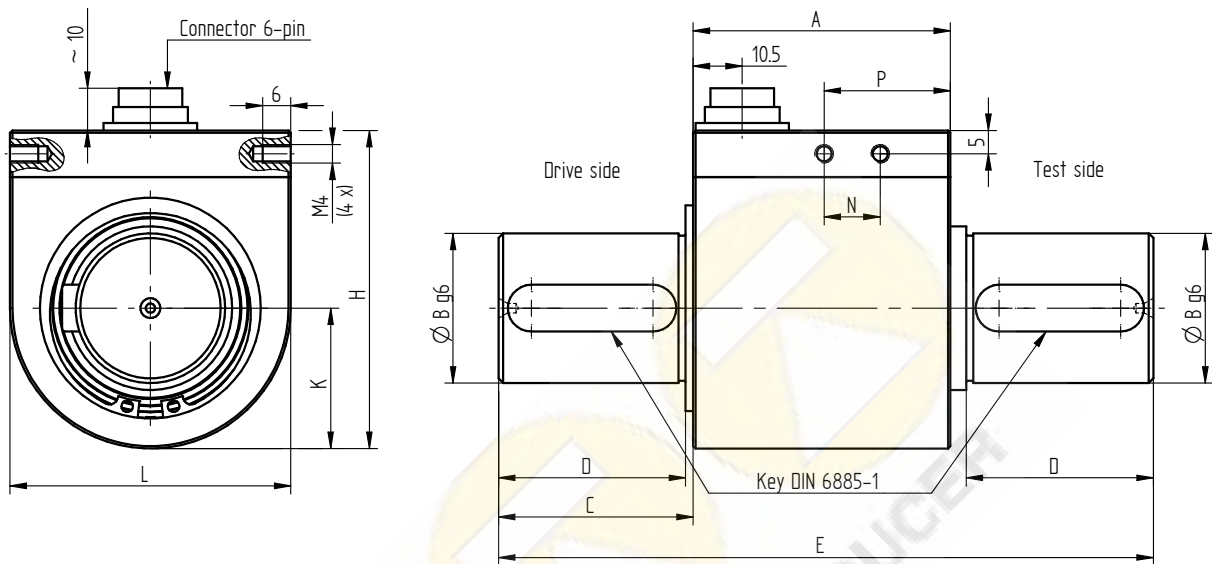


Nominal Torque [N·m]

1/2/5/10

Weight [kg]

0.2



Nominal Torque [N·m]	Dimensions [mm]										Weight [kg]
	A	ØB	C	D	E	H	K	L	N	P	
20/50	47.4	15	21.1	20	90	54	21	42	9.5	20.5	0.4
100	47.4	18	24.1	22	95	54	21	42	9.5	20.5	0.5
200/500	55	32	41.6	40	140	68	30	60	12	27	1.3

## Connection Assignment

6-pin	DR-2	Series 723
Pin 1	Excitation (-)	
Pin 2	Excitation (+)	
Pin 3	Shield	
Pin 4	Signal (+)	
Pin 5	Signal (-)	
Pin 6	Control signal (option)	

## Technical Data acc. to VDI/VDE/DKD 2639

### Rotating Slipring Torque Sensor DR-2

Nominal torque $M_{nom}$	N·m	1 ... 500
Accuracy class	% $M_{nom}$	0.1
Relative repeatability error in unchanged mounting position $b'$	% $M_{nom}$	±0.05
Rated characteristic value $C_{nom}$	mV/V	1 [1 N·m; 0.5] ±0.1%
Bridge resistance $R_{Br}$	Ω	350
Operating range of excitation voltage SG	VDC	2 ... 12
Electrical connection		6-pin series 723 <sup>1</sup>
Reference temperature $T_{ref}$	°C	23
Rated temperature range	°C	5 ... 50
Operating temperature range	°C	-10 ... 60
Temperature effect on zero signal $TK_0$	% $M_{nom}/10$ K	±0.4
Temperature effect on characteristic value $TK_C$	% $M_{nom}/10$ K	±0.2
Maximum operating torque $M_G$ (static)	% $M_{nom}$	150
Torque limit $M_{max}$ (static)	% $M_{nom}$	200
Breaking torque $M_B$ (static)	% $M_{nom}$	>300
Durability of brushes	rev.	5x10 <sup>7</sup>
Permissible oscillation stress when subjected to torque $M_{df}$	% $M_{nom}$	70 (peak-to-peak)
Level of protection		IP50

Article-No.	Nominal Torque [N·m]	Limit Speed [min <sup>-1</sup> ]	Springrate [N·m/rad]	Mass Moment of Inertia [kg·m <sup>2</sup> ]		Axial force limit [N] <sup>2</sup>	Lateral force limit [N] <sup>2</sup>
				Drive Side	Test Side		
100414	1	2000	2.1E+02	1.3E-06	3.1E-07	380	6
100413	2	2000	2.1E+02	1.3E-06	3.1E-07	380	6
100412	5	2000	5.5E+02	1.4E-06	3.3E-07	690	14.5
103852	10	2000	6.4E+02	1.4E-06	3.3E-07	780	15.5
101065	20	1500	4.1E+03	1.2E-05	6.7E-06	1750	53
101006	50	1500	1.1E+04	1.2E-05	7.0E-06	3300	135
101066	100	1500	1.9E+04	1.4E-05	8.6E-06	5200	260
100880	200	1000	5.4E+04	9.6E-05	6.7E-05	8500	340
100407	500	1000	9.0E+04	1.0E-04	7.3E-05	15000	850

### Options

Article-No.	Description	
100218	Control signal	100 % $M_{nom}$

### Calibrations

Article-No.	Description	
400676	Linearity diagram in accordance to factory standard	25 % steps
400664	Linearity diagram in accordance to factory standard	10% steps
400961	Proprietary calibration acc. to VDI/VDE 2646	3 steps
400700	Proprietary calibration acc. to VDI/VDE 2646	5 steps
400688	Proprietary calibration acc. to VDI/VDE 2646	8 steps
	DAkkS-Calibration/Standard on request	

<sup>1</sup> Female cable connector in scope of delivery at first delivery

<sup>2</sup> Unsupported shaft

## Accessories

### Electrical Connection

Article-No.	Description
10301	Female cable connector 6-pin series 581
10315	Female angled connector 6-pin series 682
10266	Connection cable, 3 m, with 6-pin female cable connector series 581 and free strands
10387	Connection cable angled, with 3 m, 6-pin female angled connector series 682 and free strands

### Amplifiers

Examples of suitable amplifiers for the slipping torque sensor DR-2:

LCV	SI-USB	GM 40	GM 80	GM 80-PA
				

